

## **Ultra-Compact Embedded Peripheral for Wearable and Robotic Vision**

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The Efference M1 is a WiFi and Bluetooth-enabled embedded peripheral engineered for wrist and head-mounted applications in robotics, drones, and monocular systems. It delivers high-resolution imagery, a wide field of view, and precise localization and mapping; all while performing on-device inference with extreme resource efficiency.

Housed in an ultra-compact, modular form factor, the M1 functions as a versatile peripheral. It synchronizes seamlessly with other Efference devices or connects to USB-C enabled iPhones, utilizing a single cable for both power and ultra-fast, low-latency data transfer

# M1 General Specifications

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## High-Performance Global Shutter Sensors

Capture high-speed motion with clarity using a best-in-class 2.3MP global shutter sensor, engineered with High Dynamic Range (HDR) and superior low-light sensitivity to perform in the most challenging lighting conditions.

## Precision 6-DOF Inertial Measurement

Achieve ultra-low latency pose estimation and image stabilization through our proprietary sensor fusion algorithms, which integrate data from a 6-DOF IMU for stable, high-frequency spatial awareness.

## Wireless Connectivity & Control

Bridge the gap between training and reality with integrated WiFi and Bluetooth; collect training data wirelessly and deploy to downstream robots with zero distribution shift, ensuring your models perform exactly as tested.

## Seamless iPhone Compatibility

Streamline portable deployments by utilizing a USB-C enabled iPhone for simultaneous power and high-bandwidth data transfer, eliminating the need for bulky external batteries while significantly reducing system weight, cabling complexity, and cost.

## Compact and Modular

Engineered to disappear into your build, this device packs full functionality into a quarter-sized footprint, allowing for seamless, unobtrusive integration into space-constrained deployments.

## Efficient Edge Compute

Run lightweight models at the edge with 1.5 TOPS of compute, capable of running distilled and quantized depth, ISP, and hand-tracking models locally.

# M1 Detailed Specifications

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## Dual Image Sensors

Sensor Type	1/2.6" 2.3MP RGB
Pixel Size	3.0µm x 3.0 µm
Shutter	Electronically Synchronized Global
Output Resolution	1920x1200 @ 60, 30, 15, 5, 1 fps 1920x1080 @ 60, 30, 15, 5, 1 fps [cropping mode] 960x600 @ 120, 60, 15, 5, 1 fps [binning 2x2 mode]
Dynamic Range	91.5 dB
Sensitivity	9606 mV/lux*s

## Physical

Dimensions	28.0 x 24.0 x 32.0 mm (1.10 x 0.94 x 1.26")
Weight	50g (0.77 lbs)
Interfaces	USB-C 3.2, Wi-Fi 6, Bluetooth 5
Mounting Options	Universal fast unlock system (bottom)
Power	USB-C 3.0 (PoC)
Operating Temperatures	-20 °C to 60 °C

## Optics

Focal Length	2.3mm (0.1")
Field of View	Max. 147° (H) x 94° (V) x 172° (D)
Aperture	f/2.0
TV Distortion	<-29.6%

## Compute

CPU	Dual-core, up to 1.0 GHz
Memory	2 GB
NPU	1.5 TOPS @ INT8

## Motion

Accelerometer Range	+/- 16G
Accelerometer Resolution	0.48 mg
Accelerometer Noise Density	4.0 mg
Gyroscope Range	+/- 1000 dps
Gyroscope Resolution	0.04 mg
Gyroscope Noise Density	0.08 dps
Output Data Rate	400Hz

# H1 Technical Drawings

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